

# Measurement of interseismic strain accumulation across the North Anatolian Fault by satellite radar interferometry

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**Abstract.** In recent years, interseismic crustal velocities and strains have been determined for a number of tectonically active areas through repeated measurements using the Global Positioning System. The terrain in such areas is often remote and difficult, and the density of GPS measurements relatively sparse. In principle, satellite radar interferometry can be used to make millimetric-precision measurements of surface displacement over large surface areas. In practice, the small crustal deformation signal is dominated over short time intervals by errors due to atmospheric, topographic and orbital effects. Here we show that these effects can be overcome by stacking multiple interferograms, after screening for atmospheric anomalies, effectively creating a new interferogram that covers a longer time interval. In this way, we have isolated a 70 km wide region of crustal deformation across the eastern end of the North Anatolian Fault, Turkey. The distribution of deformation is consistent with slip of 17–32 mm/yr below 5–33 km on the extension of the surface fault at depth. If the GPS determined slip rate of  $24 \pm 1$  mm/yr is accepted, the locking depth is constrained to  $18 \pm 6$  km.

## Introduction

The use of InSAR for the measurement of large ground movements associated with earthquakes is now a well established technique [Massonnet *et al.*, 1993; Massonnet and Feigl, 1998; Bürgmann *et al.*, 2000]. Fault creep has also been measured using interferometry, *e.g.* [Rosen *et al.*, 1998]; the ground displacements caused by creep are discontinuous, producing steps in interferograms that are relatively easy to detect. Interseismic crustal deformation, however, seldom exceeds rates of a few 10's of millimetres per year distributed over 30–150 km (strain rates of  $3 \times 10^{-8} - 5 \times 10^{-7}$  yr<sup>-1</sup>) and, to date, it has proved difficult to measure using radar interferometry. To overcome the limited coherence between SAR images over long intervals, and to enhance the crustal strain signal relative to atmospheric and orbital errors, we combined multiple interferograms [Zebker *et al.*, 1997], constructed from SAR images acquired by the ERS-1 and ERS-2 satellites. In this way we create an interferogram corresponding to a time interval longer than can be obtained directly.

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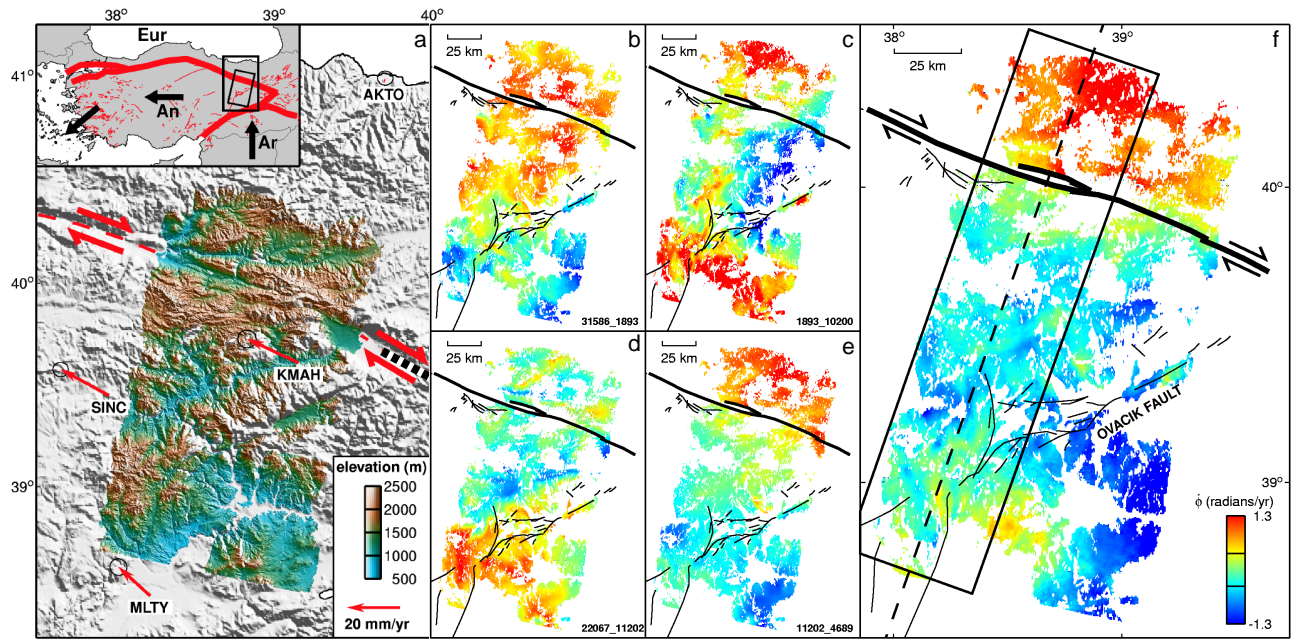
The North Anatolian Fault Zone (Fig. 1a) is one of the longest and most active strike-slip fault zones in the world [Barka, 1996]. In comparison to the analogous San Andreas Fault Zone in California, relatively little is known about the North Anatolian Fault Zone. In particular, few geodetic data exist along most of its length (east of 31°E) [McClusky *et al.*, 2000], and the distribution of interseismic strain there is unknown. It is a good target for InSAR because of its east-west orientation and the semi-arid climate in parts.

## InSAR data

We analysed 12 interferometric pairs across the North Anatolian Fault with temporal separations between 1.2 and 3.8 years and altitudes of ambiguity (the magnitude of topographic error that will cause a  $2\pi$  phase error) greater than 250 m (Fig. 2). A 40 m-resolution digital elevation model (DEM), constructed from ERS tandem pairs (Fig. 1a), was used to remove the topographic contribution to phase. The tandem DEM was calibrated by comparison to a 3-arcsecond ( $\sim 90$  m) DEM from the US Department of Defence (believed to have elevation errors  $< 50$  m). To minimise the topographic errors arising from variations in atmospheric water vapour, we constructed DEMs from 5 distinct tandem pairs, and used the one with the smallest residuals relative to the 90 m DEM. The rms residual height of this tandem DEM with respect to the existing DEM is 32 m: 0.7 radians of erroneous phase with the smallest altitude of ambiguity. In addition, the residual heights have short wavelengths ( $< 10$  km), and would not give rise to the monotonic variations in phase expected across the fault. The signal-to-noise ratio of each interferogram was improved by averaging the phase, to create datasets with 160 m pixel spacing, and by using a weighted power spectrum filter [Goldstein and Werner, 1998].

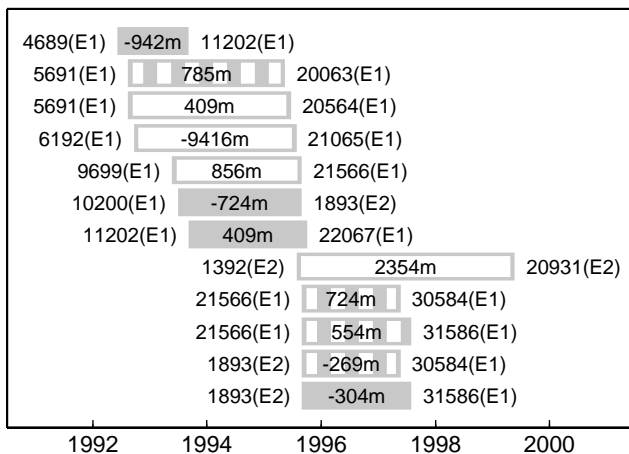
Four of the interferograms contained no usable interferometric data because of a lack of coherence. Of the coherent interferograms, four contained areas of high phase gradient, often around topographic features. These are likely to be atmospheric artefacts, arising from changes in the path length due to different amounts of atmospheric water vapour in the two images, *e.g.* [Delacourt *et al.*, 1998]. The remaining four interferograms (Fig. 1b–e) have gentle gradients: the  $1-\sigma$  variance of phase for any one interferogram is less than 3 radians. These were unwrapped interactively to remove the  $2\pi$  phase ambiguity and summed to create an interferogram with an equivalent time span of 7.4 years (Fig. 1f).

The precise orbits from Delft University [Scharroo and Visser, 1998] used in constructing the interferograms have a radial precision of  $\sim 7$  cm. Uncertainties in the satellite po-



**Figure 1.** a, Map of the eastern end of the North Anatolian Fault. The colored area shows the 40m resolution DEM that we derived using ERS tandem images (track 35, frames 2801,2819, orbits 31586(ERS-1) and 11913(ERS-2)). Outside the coloured area, shaded relief from GTOPO30 is plotted. Arrows are GPS-determined velocities relative to Eurasia [McClusky et al., 2000], and the North Anatolian Fault is marked as a dashed, red line with the location of the 1992 Erzincan earthquake shown as a dashed black line. The remainder of the fault in this area ruptured in the 1939 earthquake [Barka, 1996]. The inset illustrates schematic plate configurations (Eur=Eurasia,Ar=Arabia,An=Anatolia). b–e, Individual interseismic interferograms (orbit numbers shown), generated using the DIAPASON interferometric software (©CNES), unwrapped and scaled by the time interval so that each is an estimate of the yearly phase change ( $\phi$ ). f, Mean  $\phi$ , calculated by summing the individual unwrapped interferograms and dividing by the total time interval (7.4 years). Positive  $\phi$  (warm colors) indicate a relative decrease in distance to the satellite. The rectangular box delimits data used to construct the phase profile (Fig. 3a). Black lines are mapped faults [Şaroglu et al., 1992] with the North Anatolian Fault shown in bold.

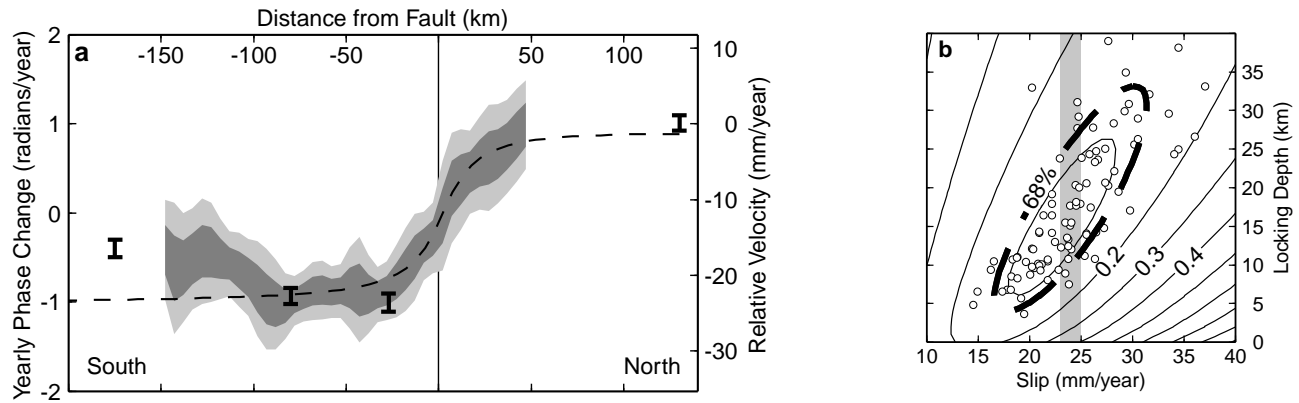
sition are greater than those in the change in position over 200 km of the satellite track, resulting in larger orbital phase



**Figure 2.** Interferometric data used. The ERS orbit numbers are shown on either side of a bar whose length represents the temporal separation of the images that form the interferogram. The scene-centre altitude of ambiguity is given at the centre of the bar. Only interferograms represented by solid bars were used in the determination of crustal strain: those represented by white bars were incoherent, strong atmospheric artefacts were exhibited in those with dashed bars. SAR data (©ESA) are from track 35, frames 2801/2819.

gradients perpendicular to the track than parallel to it. A linear gradient perpendicular to the track was removed from each interferogram to flatten the phase (Fig. 1b–e). A small erroneous phase gradient parallel to the track may still be present in each of the interferograms ( $\leq 0.5$  fringes/100 km). Because these tilts are similar to the signal expected from interseismic strain, we extended the four best interferograms for a further 100 km to the south where the deformation signal should be small. In the final stacked interferogram, we find that any small orbital errors have cancelled such that, farther than  $\sim 50$  km south of the fault, phase is approximately constant, and in good agreement with the few GPS measurements available.

The stacked interferogram (Fig. 1f) shows a strong phase change, of  $\sim 15$  radians, centred on the surface trace of the North Anatolian Fault but distributed over  $\sim 70$  km. There remains some variability ( $\sim 4$  radians), correlated over spatial wavelengths of 20–50km, that probably arises from atmospheric heterogeneities. To further enhance the deformation signal, assuming that it varies slowly along the fault, we created an averaged profile covering a 50 km wide swath of the more complete western half of the stacked interferogram (Fig. 3a). Average phase values were calculated every 5 km in 10 km bins along the profile. Although each value on the profile averages over a large number of phase measurements ( $\sim 10$ –20,000), the spatial correlation of the atmospheric errors over distances larger than the bin size means that the formal uncertainties will underestimate the actual errors. The phase variation within each 10 by 50 km bin gives a



**Figure 3.** **a**, Phase profile perpendicular to the North Anatolian Fault. The thick grey bands delimit the 1- and 2- $\sigma$  error bounds on phase, measured in the box shown in Fig. 1f. Black bars are the GPS velocities and error bounds [McClusky *et al.*, 2000] projected onto the profile and converted into phase change. The conversion from phase change to relative velocity assumes pure horizontal motion parallel to the North Anatolian Fault (vertical line). Velocities predicted by our best-fitting slip model (22 mm/yr under a 14 km elastic lid) are plotted as a dashed line. **b**, Solution-space plot for the fault model. Contours show the rms misfit (0.1 radians/yr interval) to the unperturbed phase profile. Circles are 100 best-fit parameters from a Monte-Carlo simulation of 100 perturbed profiles, each created by adding a different perturbation profile to the observed phase profile. (To account for correlated atmospheric errors, the perturbation profiles consisted of random phase values every  $L$  km, calculated using the standard error at that location, with linear ramps in between. Because atmospheric errors are correlated on a 20–50 km wavelength in these interferograms, a different value of  $L$  was chosen randomly from this range for each profile.) The errors of the model parameters are given by the distribution of solutions. The 68% confidence limit (dashed ellipse) is found to correspond to a 0.12 radians/year rms misfit to the observed phase values. The vertical grey bar corresponds to the slip rate determined from GPS.

more realistic estimate of error because it includes the long-wavelength, correlated phase signal from the atmosphere.

The section of the North Anatolian Fault covered by our interferometric data last ruptured during an earthquake in 1939 [Barka, 1996]. Hence, any post-seismic deformation is likely to be negligible, if current estimates of the time-scale for post-seismic relaxation, *e.g.* [Scholz, 1990], are correct. However, in 1992, a  $M_w=6.8$  earthquake ruptured 30 km of the North Anatolian Fault at Erzincan, 100 km east of our phase profile (Fig. 1a; [Barka and Eyidögan, 1993]). Using a viscoelastic layered earth model [Yu *et al.*, 1999], we calculated a maximum post-seismic deformation from this earthquake at our profile of 2.2 radians. Therefore, we conclude that the observed phase change represents the gradual accumulation of interseismic strain.

## Modelling of interseismic strain accumulation

To analyse the variation of phase (or displacement) across the fault, we use a simple model in which right-lateral aseismic slip,  $s$ , occurs at depth on a vertical fault beneath a locked upper crust of thickness  $d$ . For buried faults, the displacements,  $y$ , at distance  $x$  from the fault are equivalent to those caused by an infinitely-long screw dislocation in an elastic half-space ( $y = \frac{s}{\pi} \tan^{-1} \frac{x}{d}$ ) [Savage and Burford, 1973]. The model assumes pure right-lateral slip on a vertical fault. Failure to meet these conditions would produce an asymmetrical deformation pattern, which is not evident. Additional data from ascending satellite passes would enable this to be tested, but few data are available for ascending passes in this location.

The slip rate on the fault and the elastic lid thickness were determined by minimising the misfit between the model displacements, converted to phase changes, and the observed phase profile (Fig. 3a), assuming that slip at depth is coin-

cident with the surface trace of the North Anatolian Fault. The best-fit model has 22 mm/yr of slip beneath a 14 km elastic lid. The fit to this simple model is good up to distances of 100 km away from the fault. Towards the southern end of our profile the model diverges from the observations where the profile crosses the Ovacik Fault. It is tempting to ascribe this to left-lateral slip of  $\sim 5$  mm/yr on that fault. However, the sign of the phase change across the Ovacik fault reverses in the eastern half of our interferogram, and we cannot be confident that this small signal is resolvable above the atmospheric noise.

A-posteriori errors on the slip rate and fault locking depth are determined using a Monte-Carlo simulation technique (Fig. 3b). There is a clear trade-off between the fault locking depth and slip rate that arises because of the tight constraint on phase gradient near the fault: larger slip rates require deeper locking depths. Solutions within the 68% confidence ellipse range in slip rate from 17 to 32 mm/year and in locking depth from 5 to 33 km. If we use the GPS-determined slip rate of  $24 \pm 1$  mm/year, the locking depth is constrained to  $18 \pm 6$  km. The GPS slip rate is an upper bound and assumes a constant slip rate for the whole North Anatolian Fault, on a single fault strand. Nevertheless, it provides a good fit to the GPS points in this region.

## Discussion

Strain accumulation across the North Anatolian Fault is consistent with slip at depth on a single fault plane. If the accumulated elastic strain across the eastern North Anatolian Fault is eventually released in earthquakes on the locked, shallow part, then no permanent deformation will result either side of the fault. This would explain the lack of palaeomagnetic rotations along the North Anatolian Fault [Platzman *et al.*, 1994], and the apparent plate-like behaviour of Central Anatolia [Le Pichon *et al.*, 1995].

The observed distribution of deformation across the eastern end of the North Anatolian Fault clearly differs from that seen in areas of distributed strike-slip faulting like the Marlborough Fault Zone [Bourne *et al.*, 1998] and Southern California [Shen *et al.*, 1996], which probably results from distributed deformation at depth [Prescott and Nur, 1981; Bourne *et al.*, 1998]. However, because the slip at depth is filtered through the elastic upper crust, we cannot distinguish slip on a buried single fault from slip on a buried shear zone narrower than  $\sim 75$  km [Savage, 1990].

Conditions at the east end of the North Anatolian Fault are optimal for using InSAR to determine interseismic strain accumulation: relatively large rates, reasonable coherence over intervals  $\sim 2$  years, and a fault orientation almost perpendicular to the ERS descending ground track. Nonetheless, the fact that interseismic strain can be isolated there suggests that the same can be done elsewhere, even where the rates are lower and viewing geometry poorer, provided a sufficient number of suitable interferograms can be obtained. Our attempts to determine crustal deformation further west on the North Anatolian Fault failed due to the much poorer coherence that results, at the 56 mm, C-band wavelength of ERS, from the heavier vegetation there. In arid and semi-arid regions, however, coherence can be maintained for upwards of 5 years. The method described in this paper should therefore enable interseismic crustal deformation to be determined in such regions using radar interferometry.

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